

3.12. MyCNC-ET1 connection examples.

3.12.1 Motor interface connection examples.

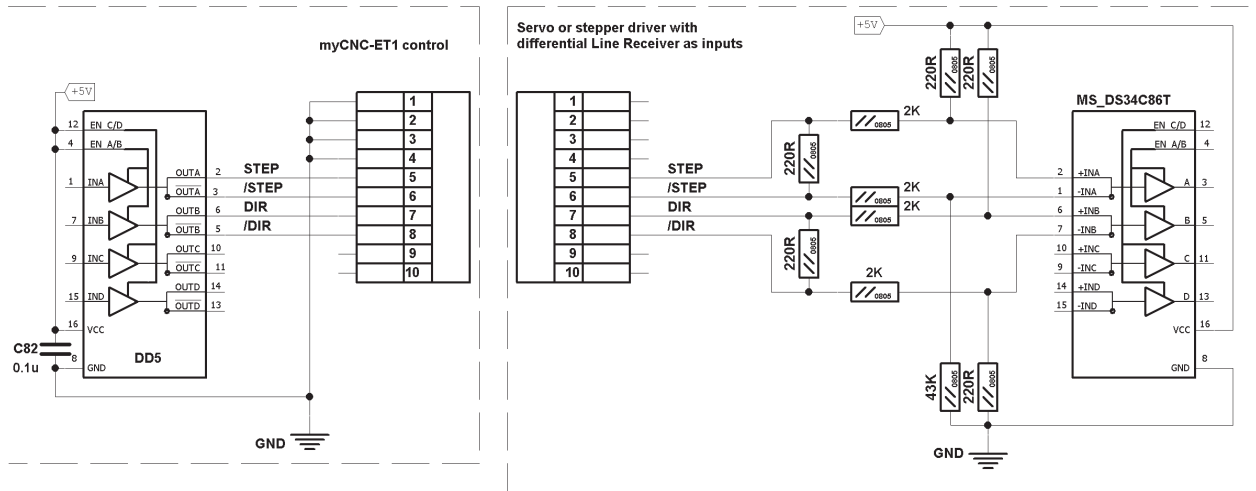


Figure 12. Connection servo or stepper driver with differential line driver as inputs.

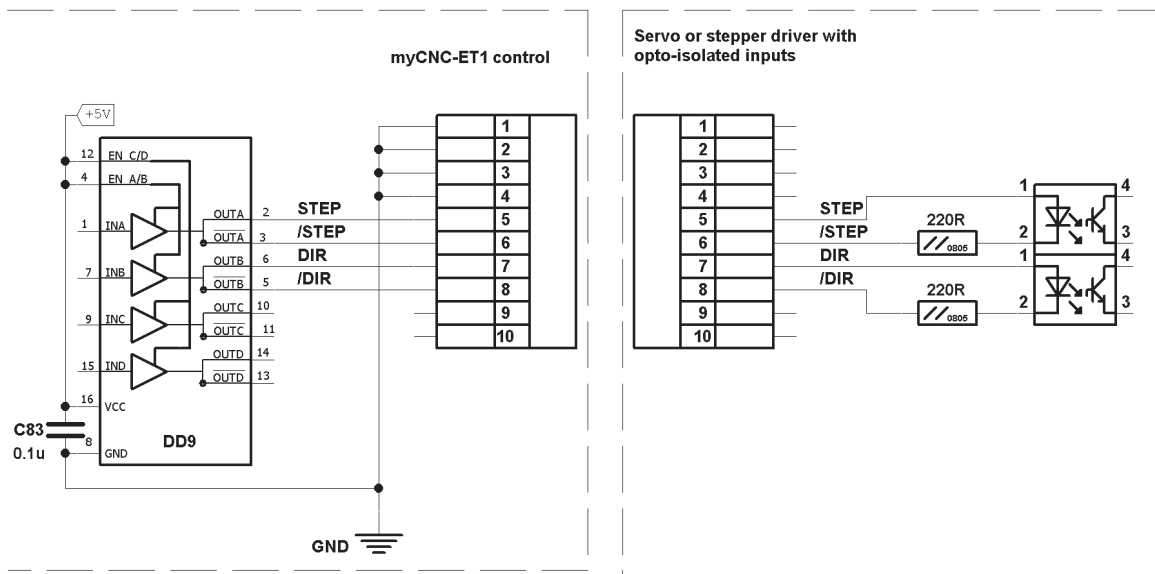


Figure 13. Connection servo or stepper driver with opto-isolated inputs.