

TROCEN[®]

Motion Control is Trocen

AWC708 Lite Motion Control

Panel Instruction

Laser Motion Control

RV 1.4

2017.06.12

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Patent

Trocen has held the patent rights for our laser motion control system.

Attention!	Users have the responsibility to point out the design error and establish protection mechanisms. Trocen does not accept any responsibility or liability for any damage or loss resulting from improper operation.
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Version

Ver. No.	Revision Date
V1.0	2015/07/17
V1.1	2015/09/17
V1.2	2015/12/17
V1.3	2016/03/09
V1.4	2017/06/12

Relevant Documents

- AWC708 Lite Panel Instruction
- LaserCAD User Manual

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Panel Preview



Button Functions

Reset

Press it to put machine back to restart state.

File

Browse the file list in the panel.

Laser

To check if laser tube will emit laser beam or not. For testing.

Box

Preview the size of pattern remaining to be machined and confirm the current position.

Origin

Set machine's home position.

Menu

Display main menu.

Stop

Stop working machine and put laser head back to preset original point.

Shift

Move the axis.

Start/Pause

Start or pause the machine and leave the laser head in current position.

Z↑/Z↓

Make laser head move up/down on Z axis and also modify value.

←/→

Move cursor.

↑/↓/←/→

Make laser head move on X or Y axis, shift between different options as well.

Z/U

Z axis auto-focus and Z, U, V and W axis motion.

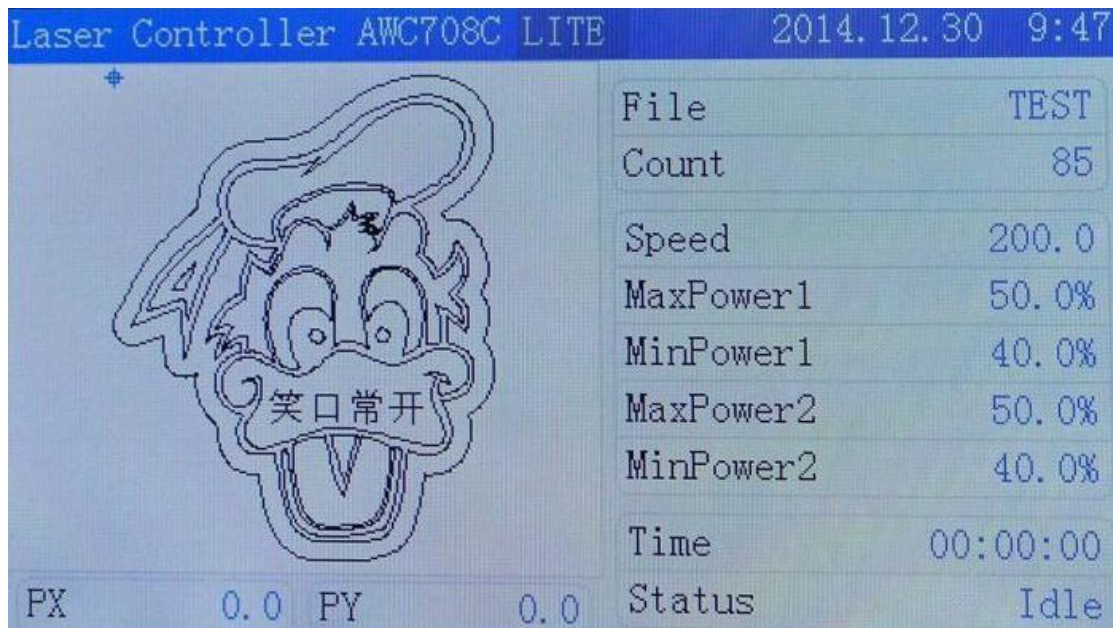
ESC

Exit from edit mode or return to previous page.

Enter

Enter edit mode and confirm the current operation.

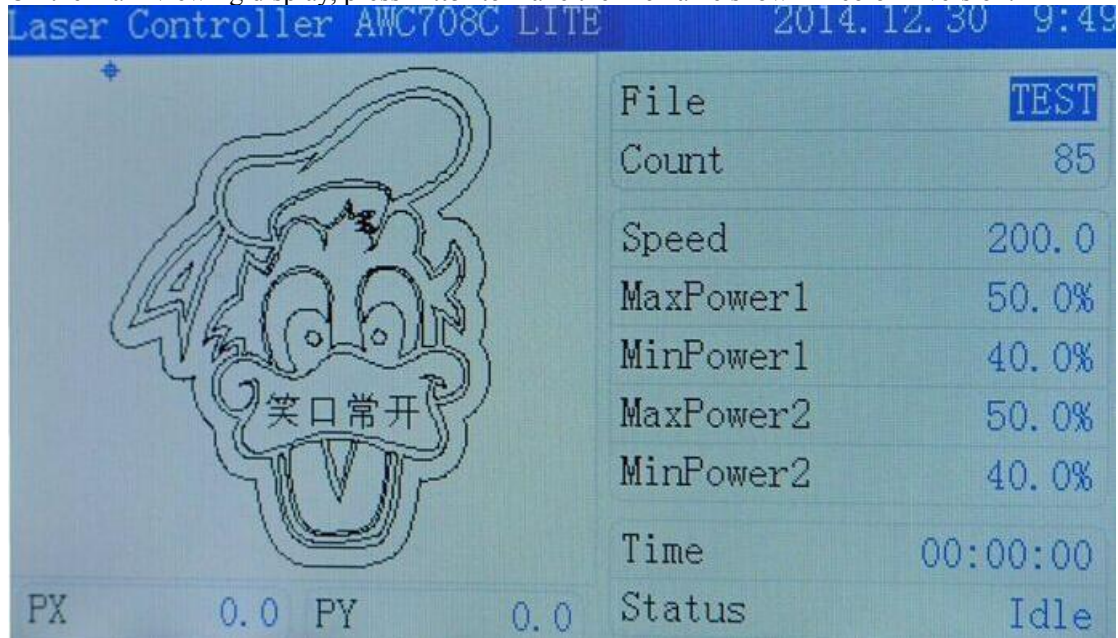
Main Viewing Display



- **Top bar**
Display software version, date and time.
- **File**
Display name of the file being processed.
- **Count**
Show the number of finished file.
- **Speed**
Display the working speed.
- **MaxPower1 MinPower1 /MaxPower2 MinPower2**
Max power means working power while min power means corner power.
- **Time**
Display the time worked.
- **Status**
Display the machine's working state including working, idle and pause state. Machining process will be showed in form of percent bar.
- **PX PY**
Display the XY coordinate.

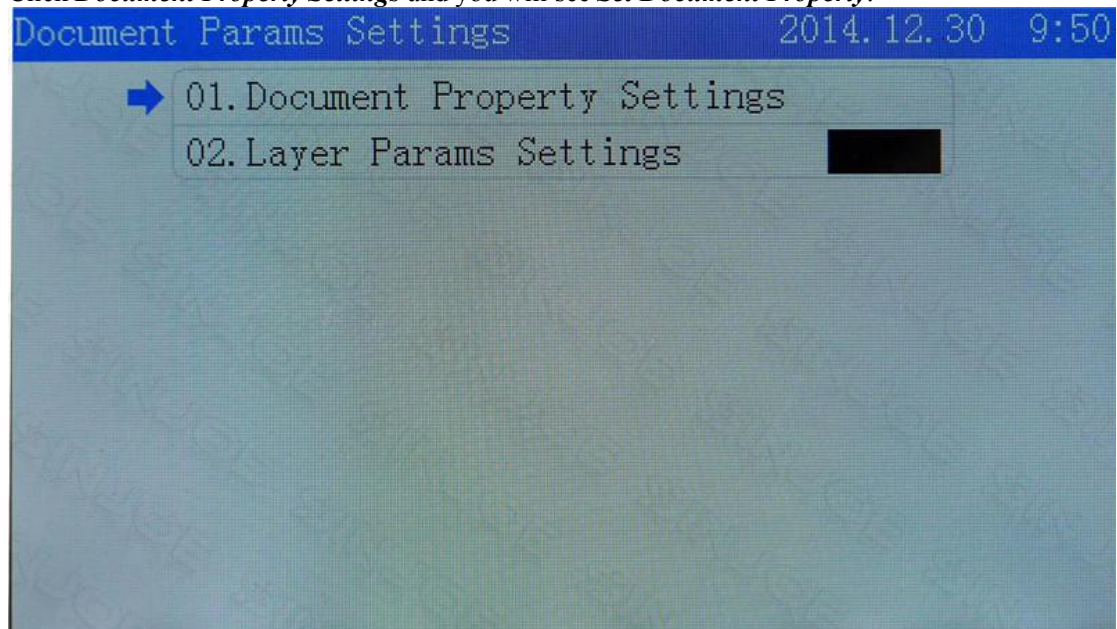
Main Menu Function

On the main viewing display, press **Enter** to make the file name shown in color inversion.



Document Parameters Settings

Click **Document Property Settings** and you will see **Set Document Property**.



You can modify some option's value by clicking **Enter** to confirm it.



The image shows a screenshot of a software interface titled "Set Document Property". The title bar includes the date and time "2014. 12. 30 9:50". The main area contains a list of properties with their corresponding values:

Property	Value
Repeat Count	10000
Repeat Delay (s)	000
Feed Distance (mm)	0000
X Size (mm)	97.2
Y Size (mm)	121.7

- **Repeat Count**
Machine repeat working times.
- **Repeat Delay(s)**
Time interval between the previous job and next job.
- **Feeding Distance(mm)**
Feeding distance for each time.
- **X Size(mm)**
The length of pattern on X axis.
- **Y Size(mm)**
The width of pattern on Y axis.

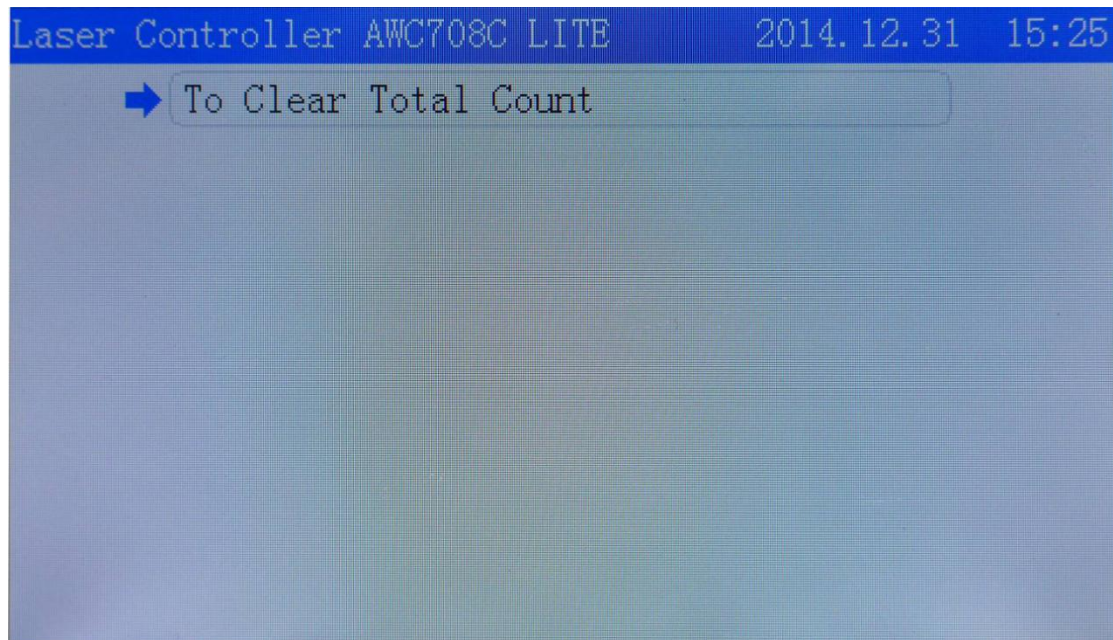
Layer Params Settings		2014.12.30 9:50
Work Mode		Cut
→ Speed (mm/s)		0100.0
MaxPower1 (%)		50.0
MinPower1 (%)		40.0
MaxPower2 (%)		50.0
MinPower2 (%)		40.0
MaxPower3 (%)		00.0
MinPower3 (%)		00.0
MaxPower4 (%)		00.0
MinPower4 (%)		00.0

Layer Parameters Settings

- **Work Mode**
Machining mode.
- **Speed(mm/s)**
Pattern processing speed.
- **Max Power**
The max working power of laser head.
- **Min Power**
The min power of laser head and also known as corner power.

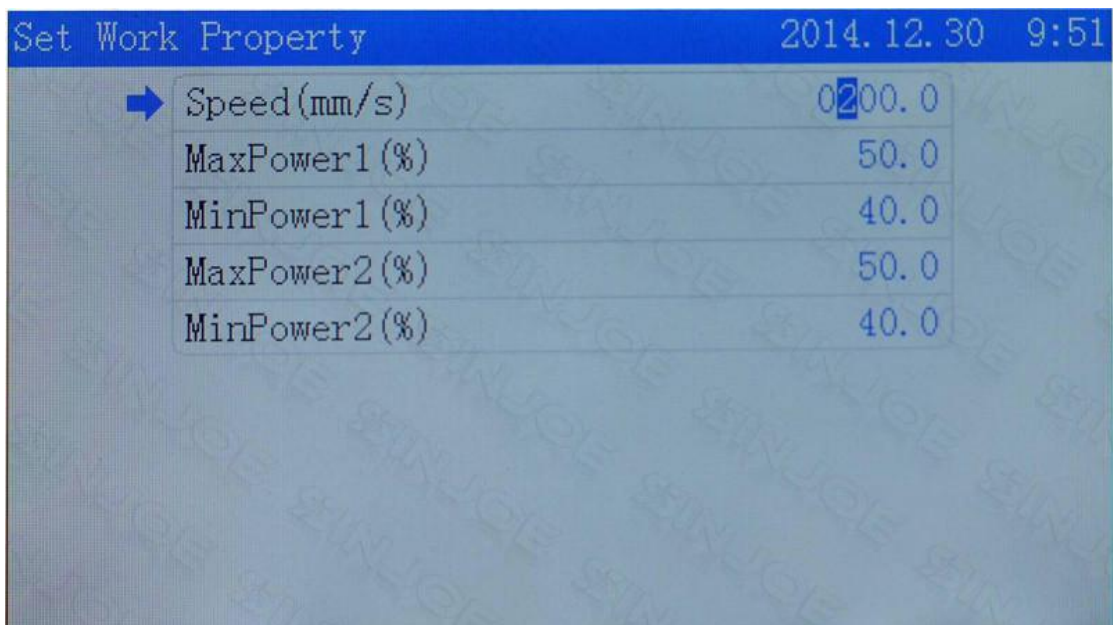
Cleaning Total Count

Click **To Clear Total Count** to clear all the machining count.



Set Work Property

Click **Speed** and you will see **Set Work Property**.



How to tell differences of **Speed**, **Max Power** and **Min Power** between **Idle**, **Pause** and **Working**?

Back to main viewing display and if the state bar on the bottom-right showing **idle**, **Speed** stands for laser head's moving speed without powering-on while **Max Power&Min Power** here stands

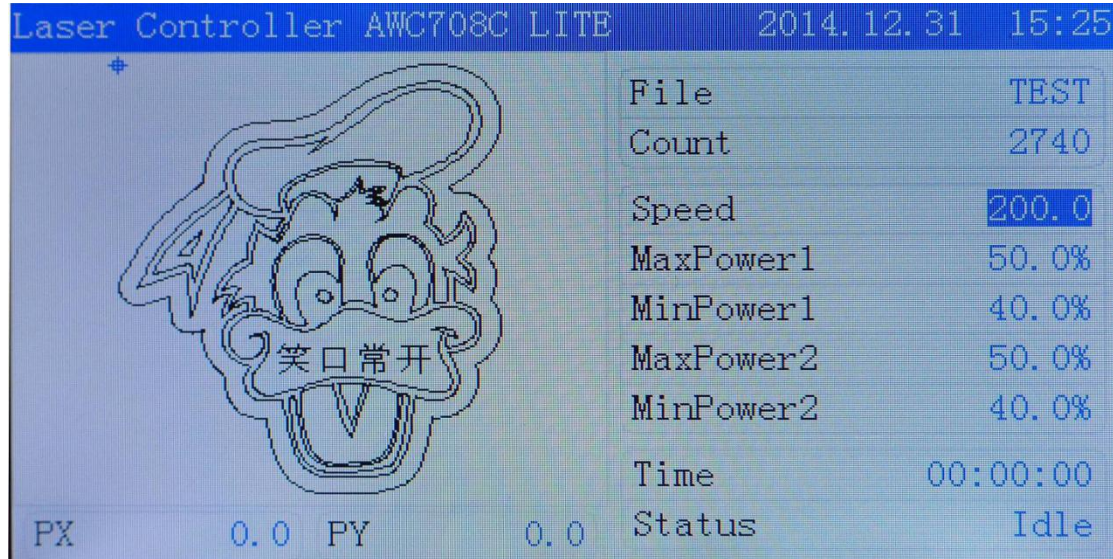
for the power of laser burst.

If the state bar on the bottom-right showing *pause* and it is valid one-time for current situation when you change the value of *Speed*, *Max Power* or *Min Power*. The changed value will not be valid for the next time cutting and it will be turned back to that of changing before instead.

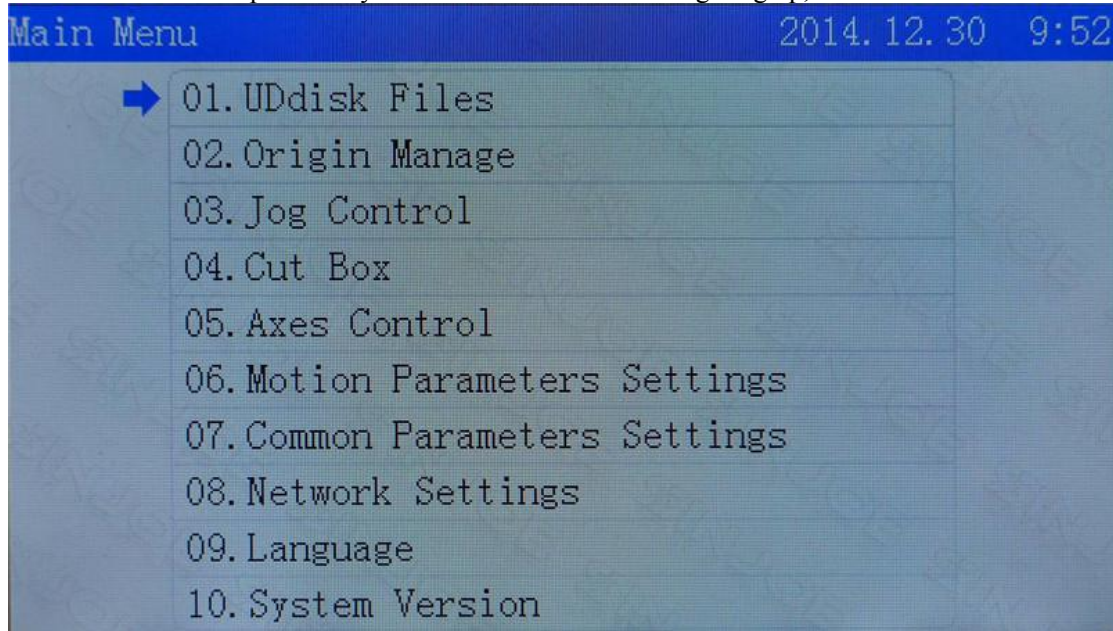
If the state bar on the bottom-right showing *working*, *Speed* stands for laser head's working speed while *Max Power*&*Min Power* here stands for working power.

Main Menu Function Settings

01. U Disk Files



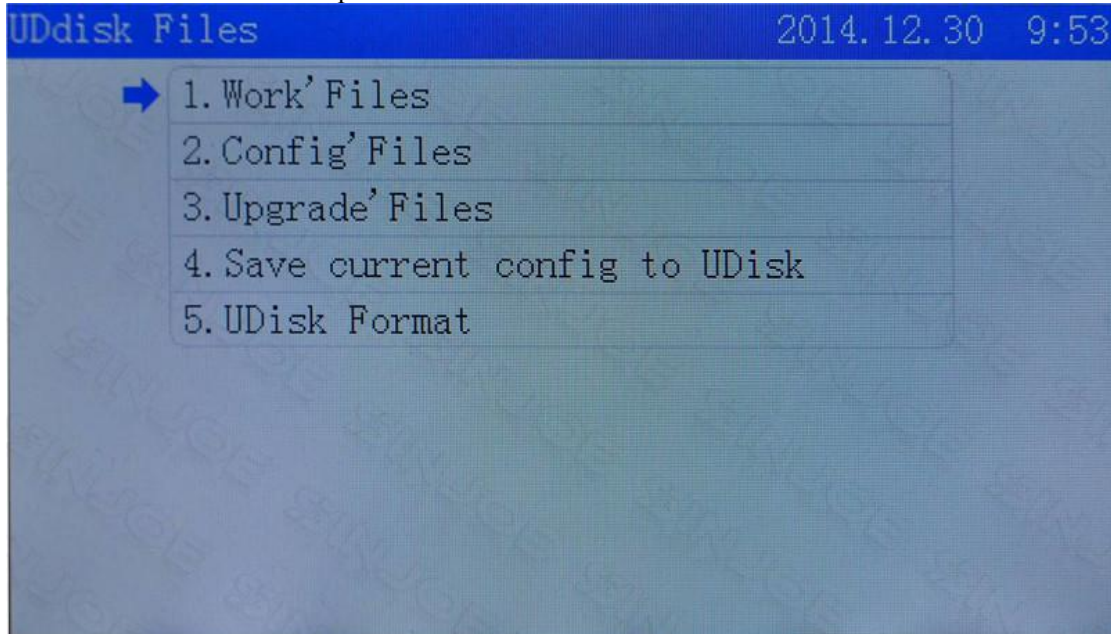
Insert U disk to USB port until you see the U disk indicator lighting up, then click **U Disk Files**.



- ① U disk should be formatted to FAT 32 File system.Quick Format is forbidden .Any other files formations are not supported.
- ② Recommend use U disk with Indicator to ensure if U disk connected successfully with main board
- ③ Please use origin and regular U disk.When the U disk has never been able to read , try to replace other U disk.

U Disk Work Files

Click **Work' Files** and you can browse file number and also shift pages left to right by clicking ←/→ when the number of imported files is more than 10.



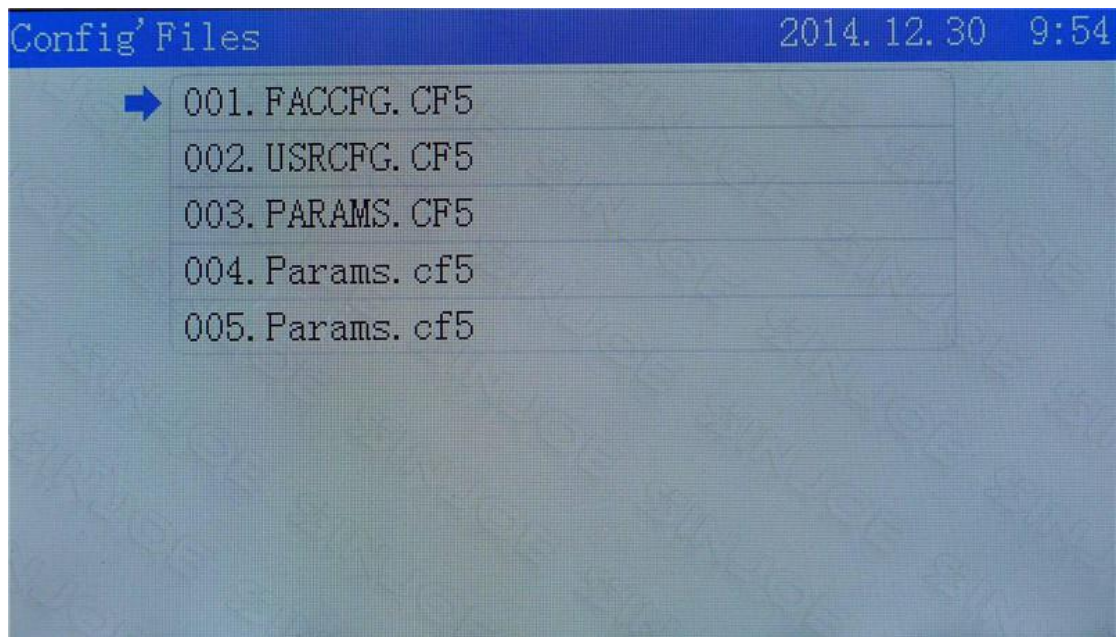
You can see pattern previewing on the right side and click **Enter** to copy the working file from U disk to main board storage.



The working file in U disk means off-line file saved in U disk that with file suffix ud5. Files with JPEG formation saved in U disk cannot be read directly.

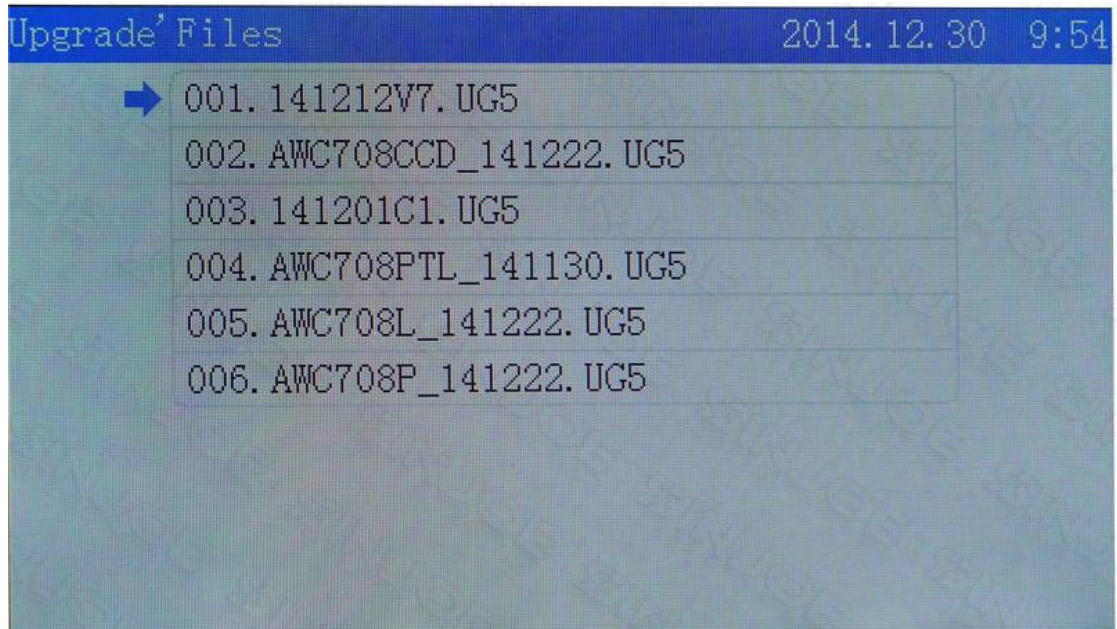
Config Files

Click **Config' Files**, then pick up the file you need to upgrade.



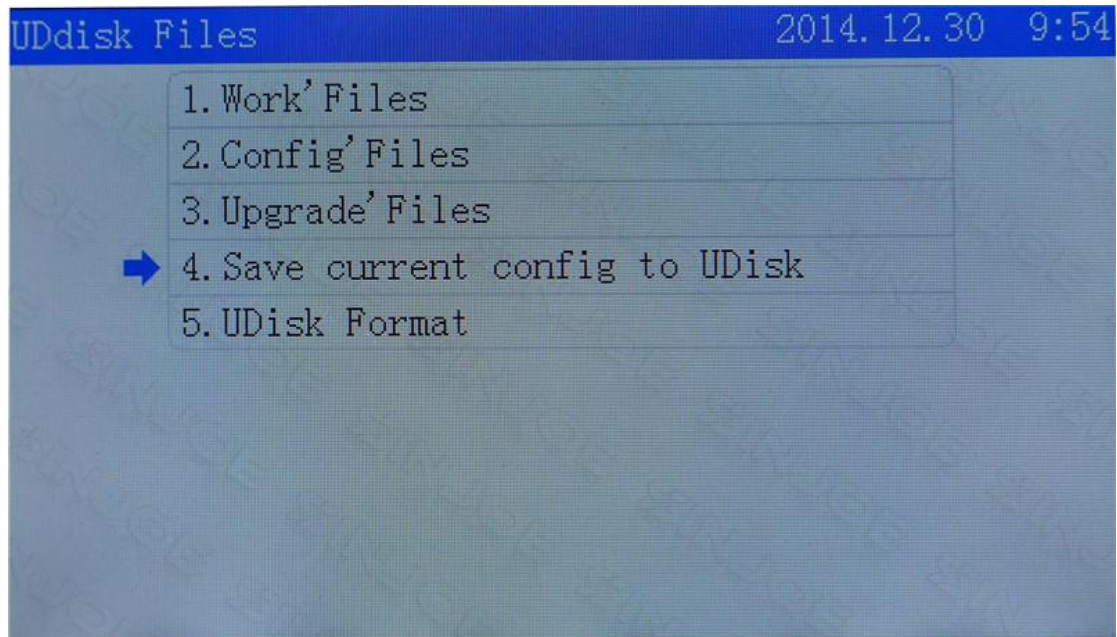
Upgrade Files

Click **Upgrade' Files**, then choose the file you need to upgrade. The upgraded file of LITE series is AWC708L while those of PLUS series is AWC708P.



Do not cut off electricity before upgrade finished, otherwise, it may lead a burnt out of main board. Upgrade will last for 30 seconds and then auto reset.

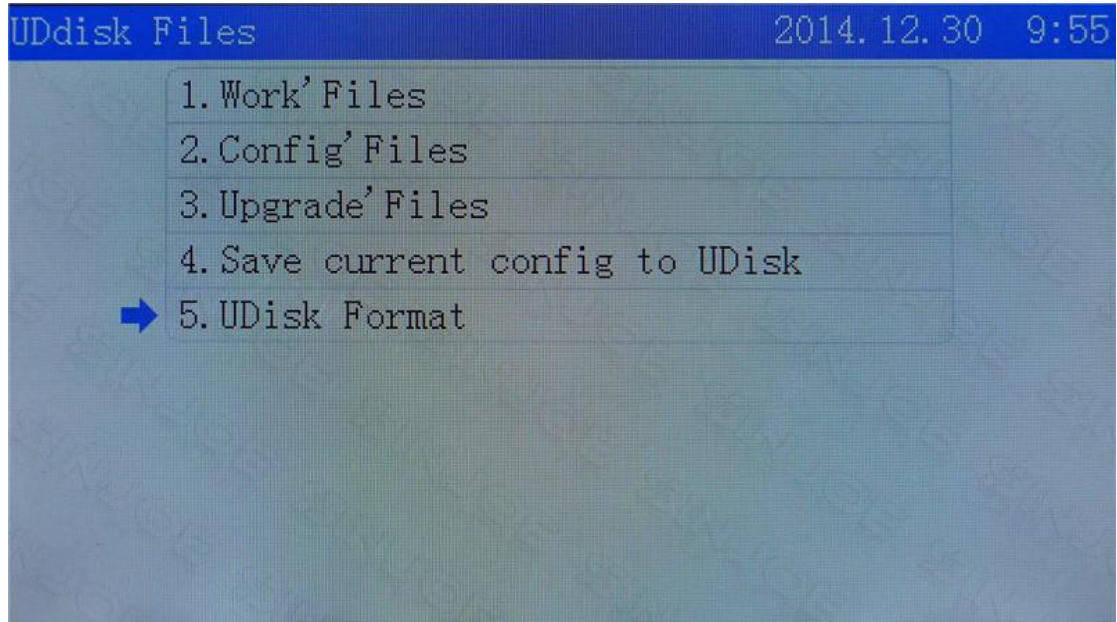
Save Current Config to U Disk



Click *Save Current Config to U Disk* and the file will be saved as the name of '*Params.cf5*'.

U Disk Format

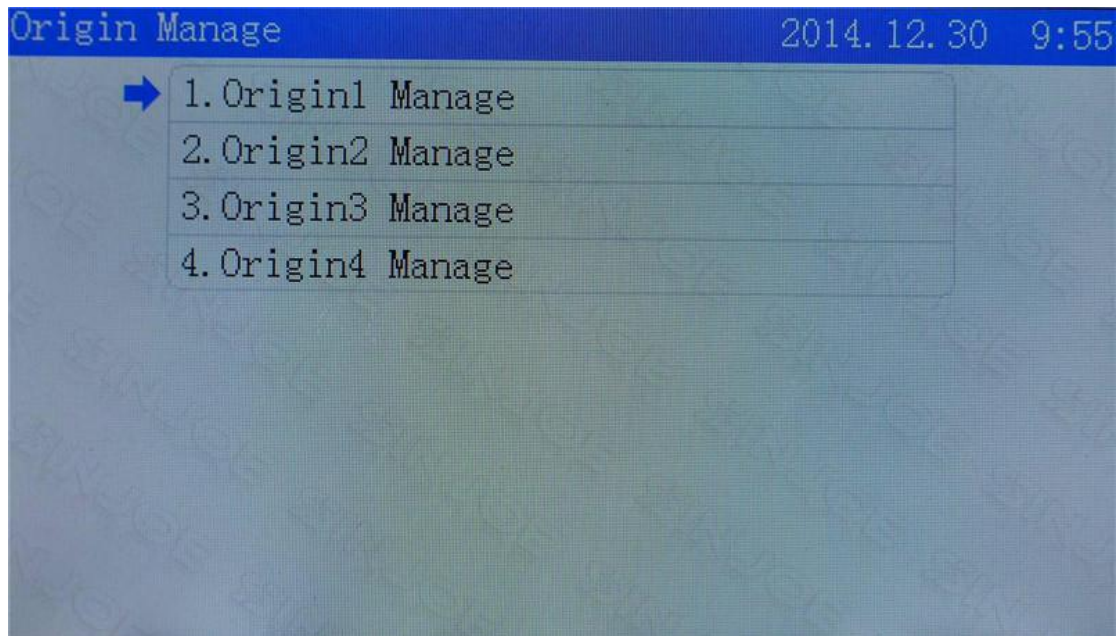
Click *U Disk Format*.



All files will be lost if you click '*U Disk Format*'.

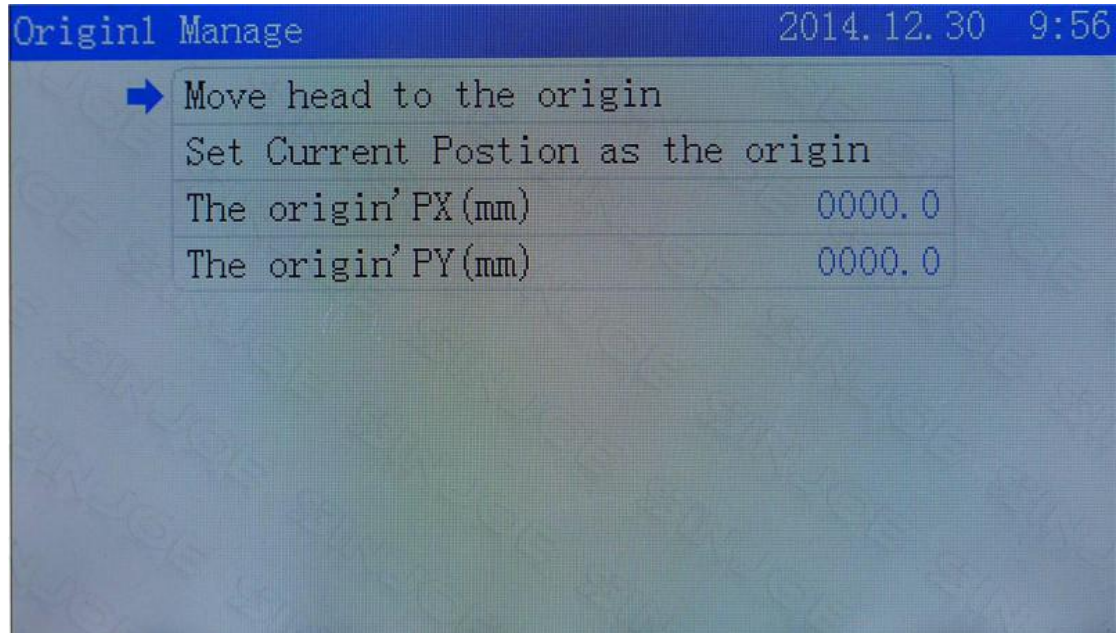
02. Origin Manage

Go back to main menu and click **Origin Manage**.



Click **Origin1 Manage** and **Set Current Position as the Origin** to set the current position as origin point.

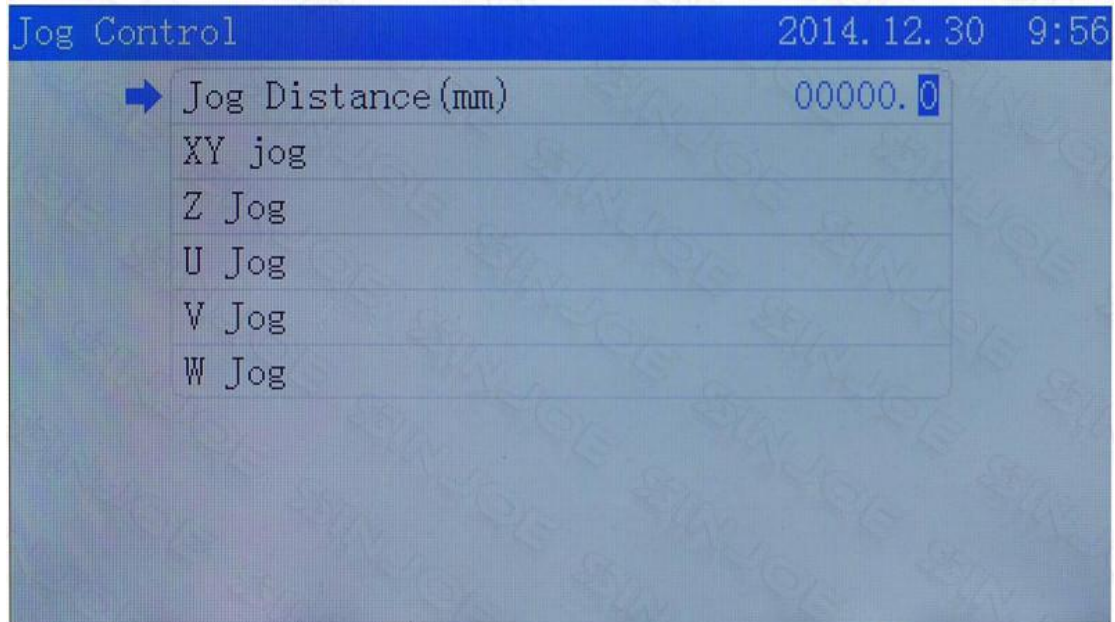
Turn to '**The origin'PX(mm)**' and '**The origin'PY(mm)**' to modify coordinate position of origin point.



03. Jog Control

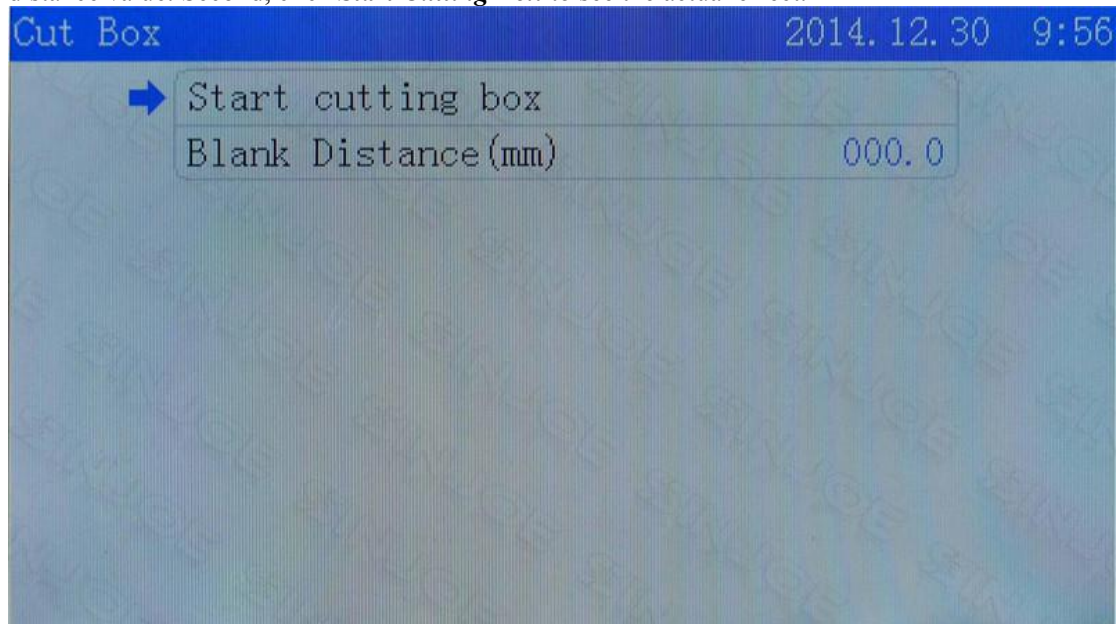
Go back to main menu and click **Jog Control**, then **Jog Distance** and modify the distance of one step.

On **Jog Control**, click **Z↑**, **Z↓** to move cursor to relative jog axes. Click **↑**, **↓**, **←**, **→** to control movement of each axis.



04. Cut Box

Go back to main menu and click **Cut Box** and turn to **Blank Distance** at first to modify the distance value. Second, click **Start Cutting Box** to see the actual effect.

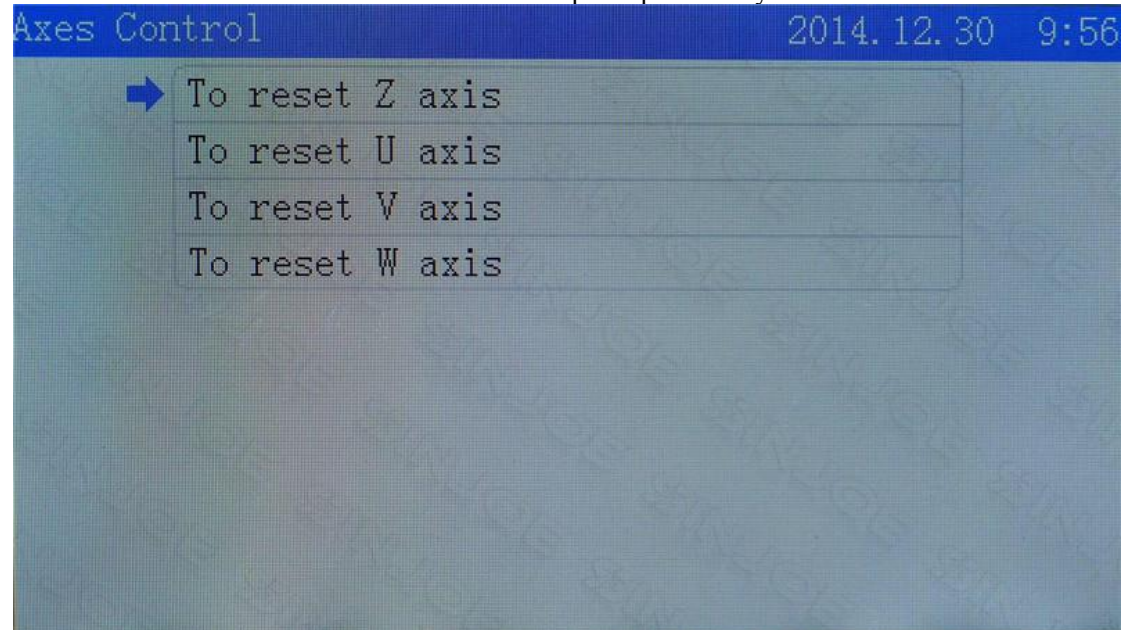


- **Blank Distance(mm)**

The distance between cutting pattern border box and actual cutting box.

05. Axes Control

Go back to main menu and click *Axes Control* to pick up the axis you need to reset.



06. Motion Parameters Settings

Go back to main menu and click **Motion Parameters Settings**, modify the value.

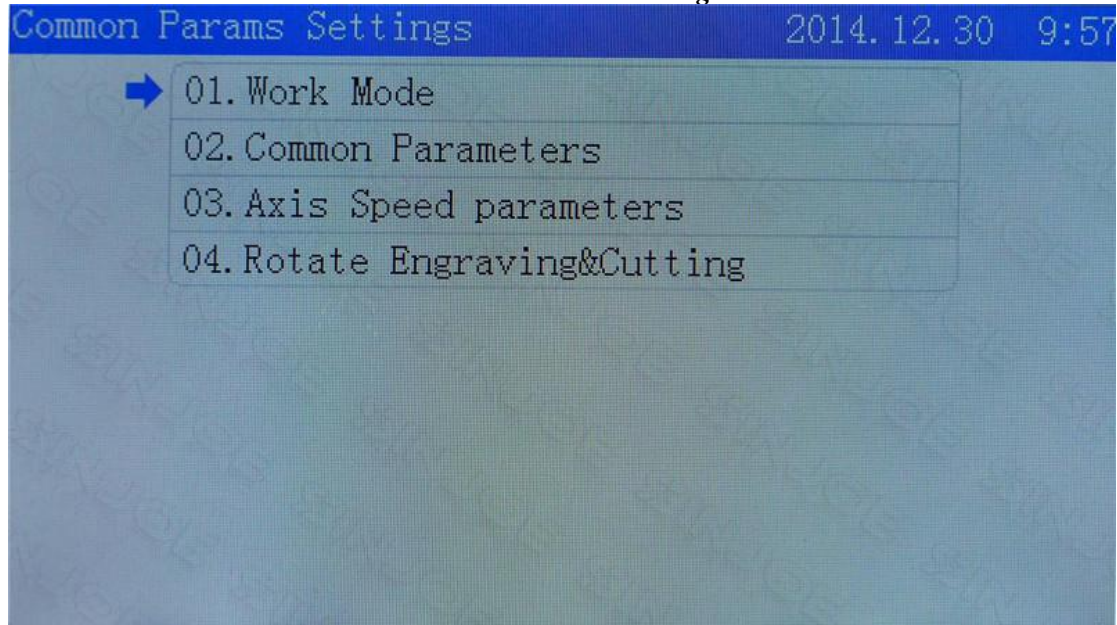
Motion Parameters Settings		2014.12.30	9:57
→	Space Speed (mm/s)	0300.0	
	Cut Jerk (mm/s ³)	050000	
	Space Jerk (mm/s ³)	080000	
	Min Acc (mm/s ²)	00150	
	Cut Acc (mm/s ²)	03000	
	Space Acc (mm/s ²)	03000	
	Engrave Acc (mm/s ²)	10000	
	Start Speed (mm/s)	10.0	
	Speed Factor	3.0	

- **Space Speed(mm/s)**
Also known as air-travel speed. The speed of laser head moving without laser powering on and should be filled in the number with an increase or decrease of 50 each time.
- **Cut Jerk(mm/s³)**
The variation of cutting acc and should be filled in with the number of an increase or decrease of 10 thousand each time.
- **Space Jerk(mm/s³)**
Also known as air-travel jerk. The variation of laser head's moving speed acc without laser powering on and should be filled in the number with an increase or decrease of 10 thousand each time.
- **Min Acc(mm/s²)**
This option should be filled in number with an increase or decrease of 50 or 100 at a time at least.
- **Cut Acc(mm/s²)**
The variation of cutting speed and should be filled in with an increase or decrease of 500 each time.
- **Space Acc(mm/s²)**
The variation of laser head's moving speed without laser powering on and should be filled in the number with an increase or decrease of 500 each time.
- **Engrave Acc(mm/s²)**
The variation of engraving speed and is only effective to engraving.
- **Start Speed(mm/s)**
The initial speed of laser head from static condition to movement.
- **Speed Factor**
We suggest that lower speed is going to be filled in with 0.5 or 1 while regular speed with 2 and high speed with 3 or 4.

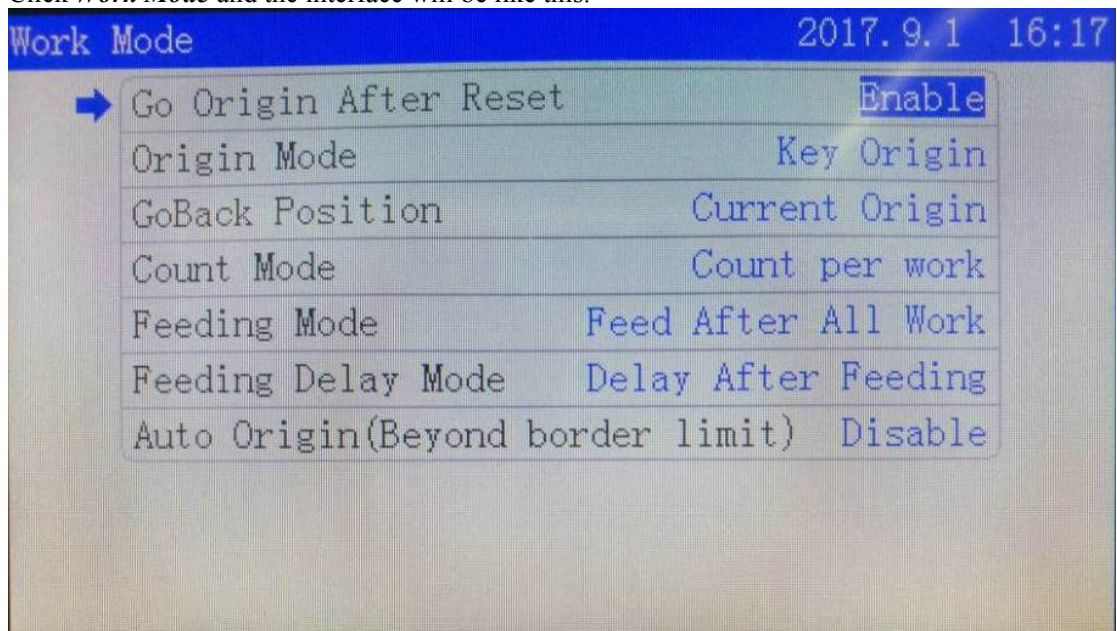
07. Common Parameters Settings

Work Mode

Go back to main menu and click *Common Parameters Settings*.



Click *Work Mode* and the interface will be like this.



Click *Go Origin After Reset* and you can choose 'Enable' or 'Disable' with ←, →.

Click *Origin Mode* and you can make choice of *Software Origin*, *Machine Zero as Origin*, *Current Position*, *Key Origin* with ←, →.

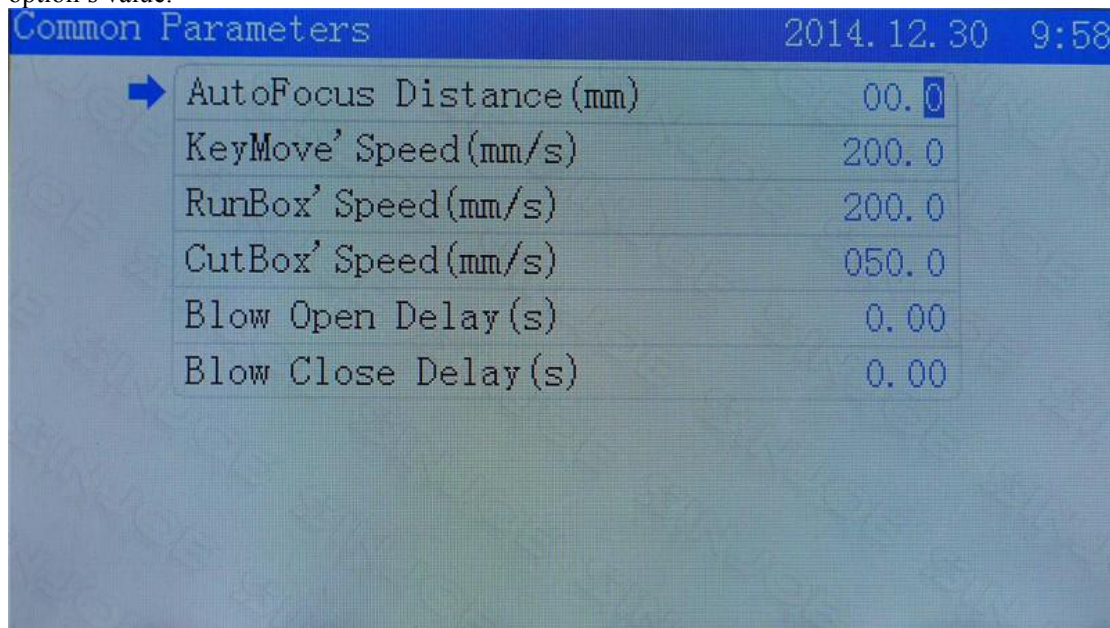
Click *Go Back Position* and you can switch over *Go Back Machine Zero*, *Current Position*, *Current Origin* with ←, →.

Click *Count Mode* and you can make choice of *Count per Work*, *Count per Light*, *Single of Array* with ←, →.

- **Go Origin After Reset**
Machine is going to reset before laser head turning back to locating point, otherwise, it will stay at machine origin point.
- **Origin Mode**
Current origin refers to laser head staying at current position.
Key origin refers to moving laser head by arrow keys to where you want and the coordinate position set is only the same as shown on panel but different from software.
Software origin refers to pattern coordinate position on software.
Machine zero refers to locating point set coincident with machine zero.
- **Go Back Position**
Current Position means laser head staying exactly at the current position after finishing job.
Current Origin refers to laser head going back to set locating point after finishing job.
Go Back Machine Zero refers to laser head going back to machine zero directly after finishing job.
- **Count Mode**
Count Per Work refers to laser head cutting all the objects on one page that is counted as one.
Count Per Light refers to laser beam lighting once that is counted as one.
Single of Array refers to laser head cutting one pattern of one page that is counted as one.
- **Feeding Mode**
Feed After All Work and *Feed After Array* is allowed to selected.
- **Feeding Delay Mode**
The time interval between the previous and next job when feeding.
- **Auto Origin (Beyond Border Limit)**
Dialogue box will pop up when graphic goes beyond border limit if this option is enabled.

Common Parameters

Go back to **Common Parameters Settings** and click **Common Parameters**. You can modify the option's value.



- **AutoFocus Distance(mm)**
The distance between laser head's focus lens and origin point of Z axis.

- **KeyMove' Speed(mm/s)**
The speed of laser head moving on axis when pressing button on panel.
- **RunBox' Speed(mm/s)**
Laser head's speed of outlining cutting/engraving object area without laser powering on.
- **CutBox's Speed(mm/s)**
The speed of laser head cutting box with laser powering on.
- **Blow Open Delay(s)**
The delay at which the laser powers on.
- **Blow Close Delay(s)**
The delay at which the laser powers off.

Axis Speed Parameters

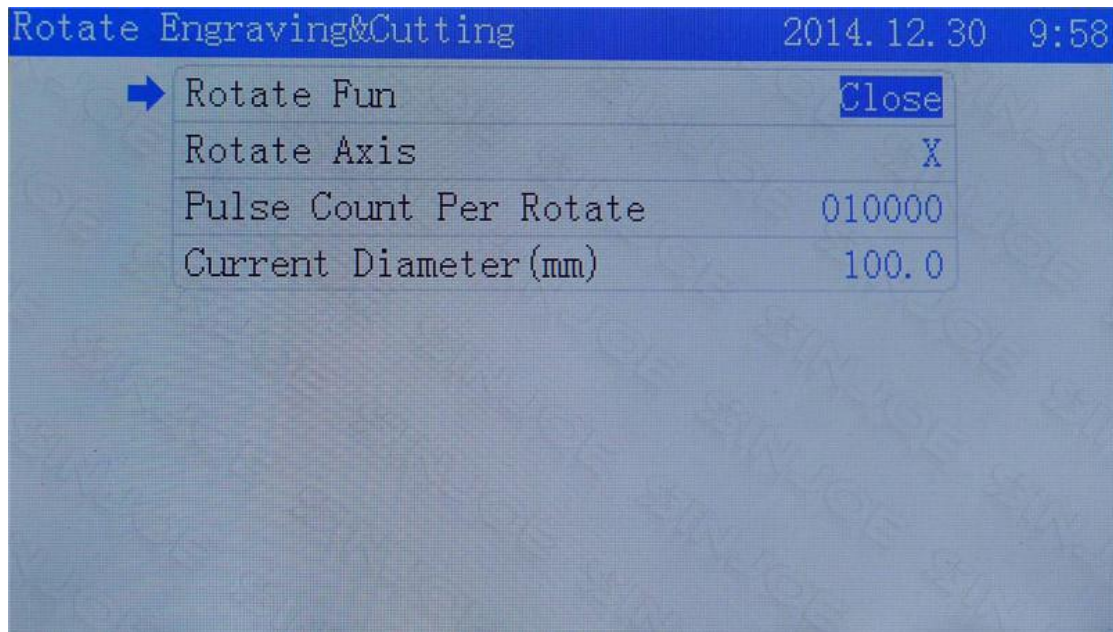
Go back to **Common Parameters Settings**, click **Axis Speed Parameters** and you can modify the value of various speed shown below.

Axis Speed parameters		2014.12.30 9:58
→ Z Work Speed (mm/s)		080.0
U Work Speed (mm/s)		200.0
V Work Speed (mm/s)		100.0
W Work Speed (mm/s)		100.0
XY Home Speed		050.0
Z Home Speed (mm/s)		040.0
U Home Speed (mm/s)		050.0
V Home Speed (mm/s)		050.0
W Home Speed (mm/s)		050.0

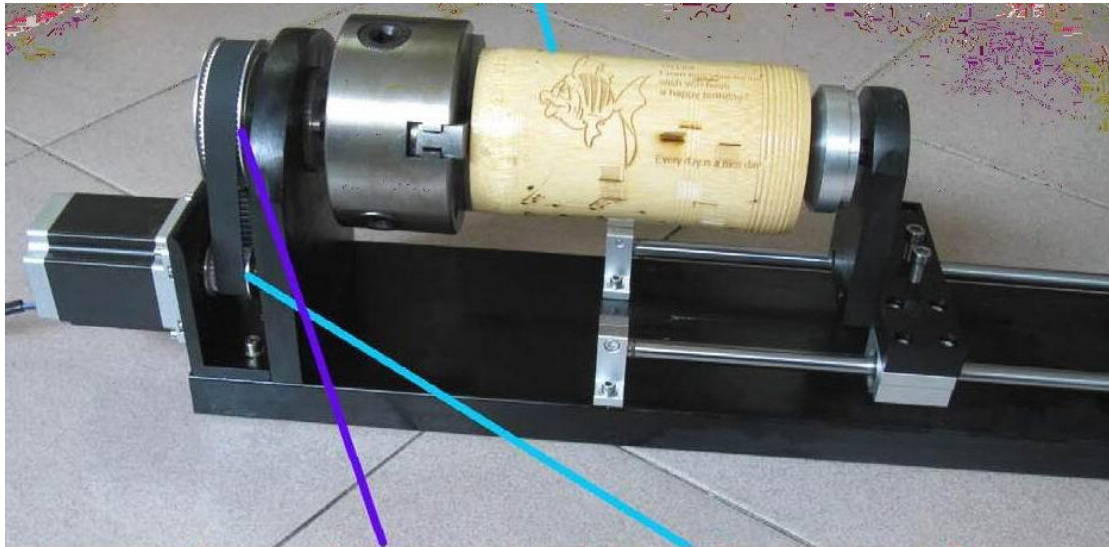
- **Z/U/V/W Work Speed**
The working speed of Z/U/V/W axis.
- **XY/Z/U/V/W Home Speed**
The reset speed of XY/Z/U/V/W axis.

Rotate Engraving & Cutting

Go back to *Common Parameters Settings*, click *Common Params Settings* and *Rotate Engraving&Cutting*. You can shift over with ←, → or modify the value.



- **Rotate Function**
The switch of rotate engraving function. Click *open* when required.
- **Rotate Axis**
It is the rotating axis for rotating and engraving function. X, Y, Z and U axis can be selected as rotate axis.
- **Pulse Count Per Rotate**
The number of pulses refers to axis rotation per week. Users can change distance per pulse of X and Y axis by comparing the expected length of a rectangle drawing on a blank sheet of paper with actual length that is needed to be measured. (Please go see Distance Per Pulse in the following page).
- **Current Diameter(mm)**
The diameter of machining workpiece.



Formula:

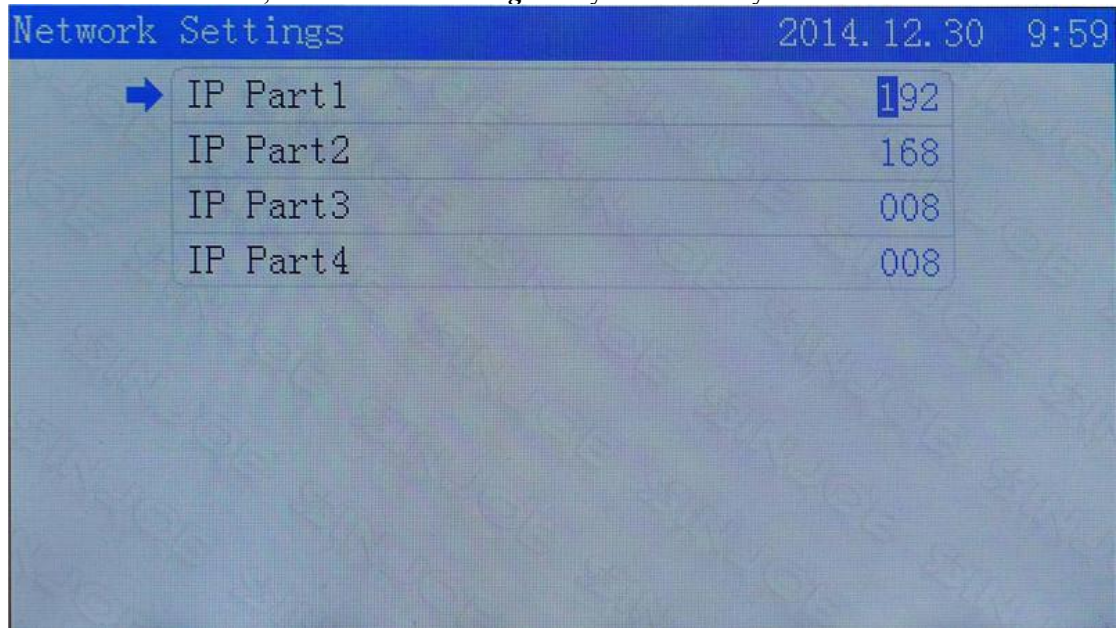
Big Gear/Small Gear=3

Driver Step*(Big Gear/Small Gear)=Current Diameter

For example, driver step is 6400, then current diameter is $6400*3=19200$. Notice: this formula is only applied for work-holding device like pic shown above.

08. Network Settings

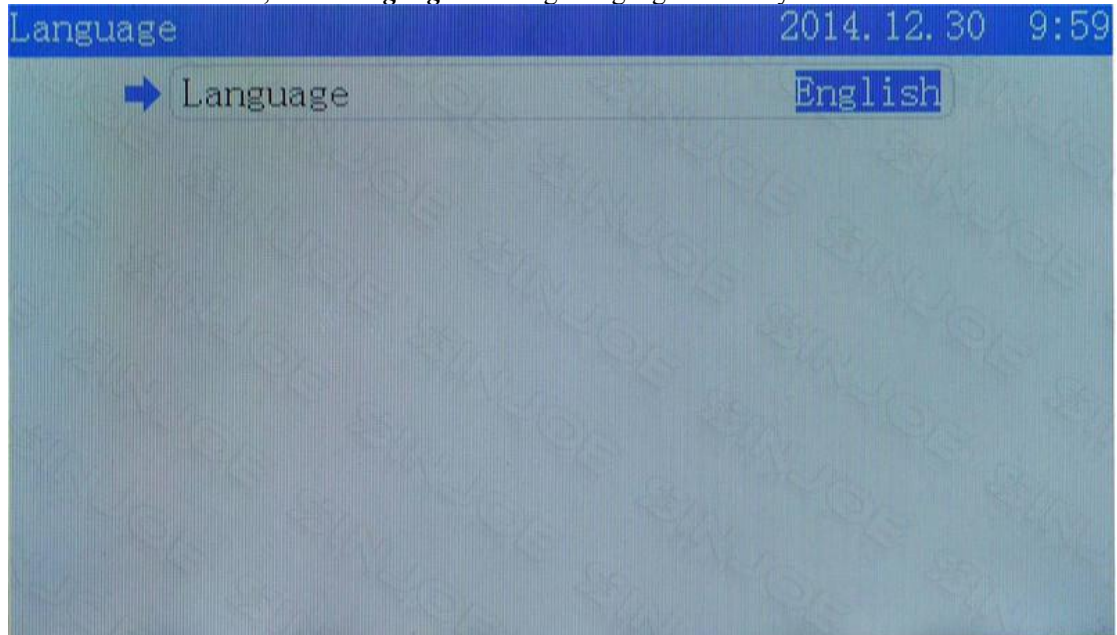
Go back to main menu, click *Network Settings* and you can modify the value.



Network Settings		2014.12.30	9:59
→	IP Part1	192	
	IP Part2	168	
	IP Part3	008	
	IP Part4	008	

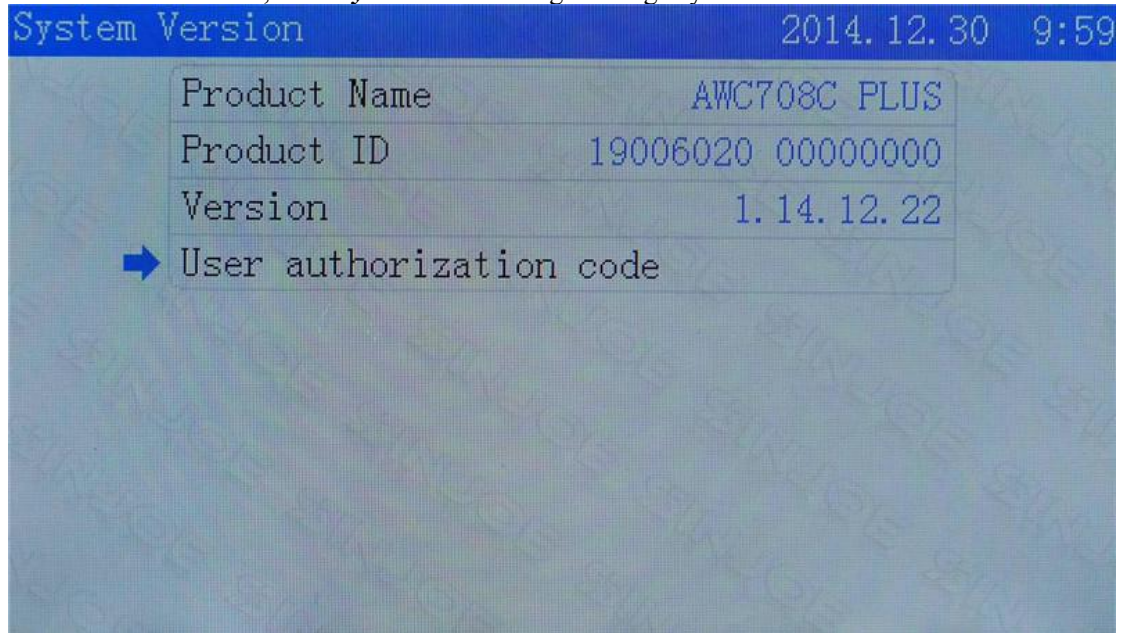
09. Language

Go back to main menu, click **Language** to change language that fits you.



10. System Version

Go back to main menu, click **System Version** to go through system info.

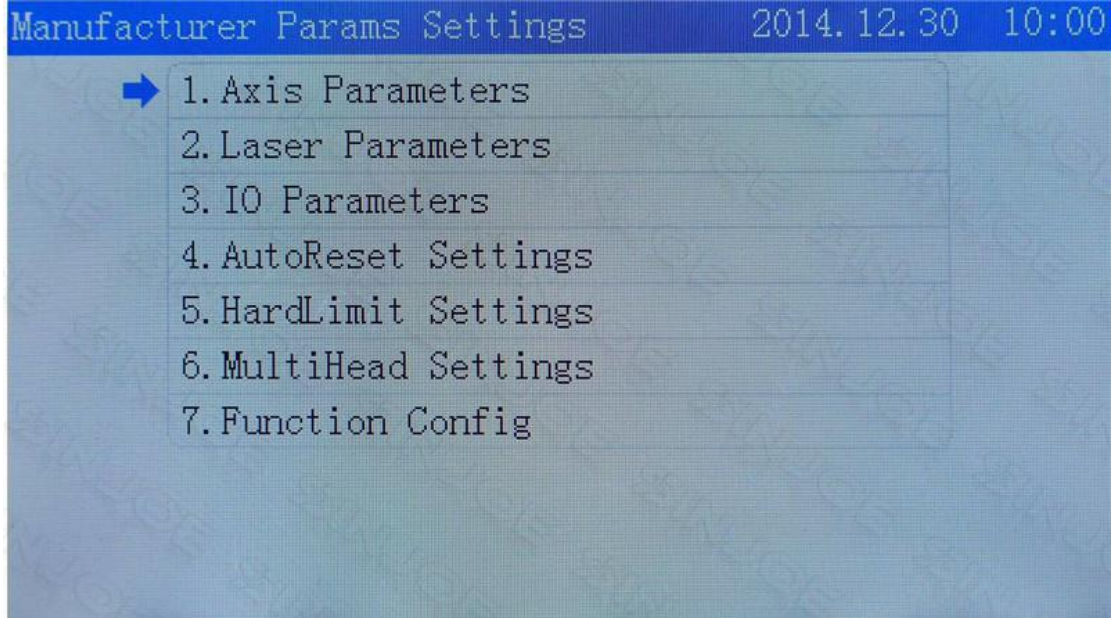


The screenshot shows a terminal-style interface with a blue header bar. The header bar contains the text "System Version" on the left and "2014.12.30 9:59" on the right. Below the header, there is a table with four rows of system information. The first row shows "Product Name" as "AWC708C PLUS". The second row shows "Product ID" as "19006020 00000000". The third row shows "Version" as "1.14.12.22". The fourth row shows "User authorization code" with a blue arrow pointing to the left, indicating it is the current selection.

System Version		2014.12.30 9:59
Product Name	AWC708C PLUS	
Product ID	19006020 00000000	
Version	1.14.12.22	
→ User authorization code		

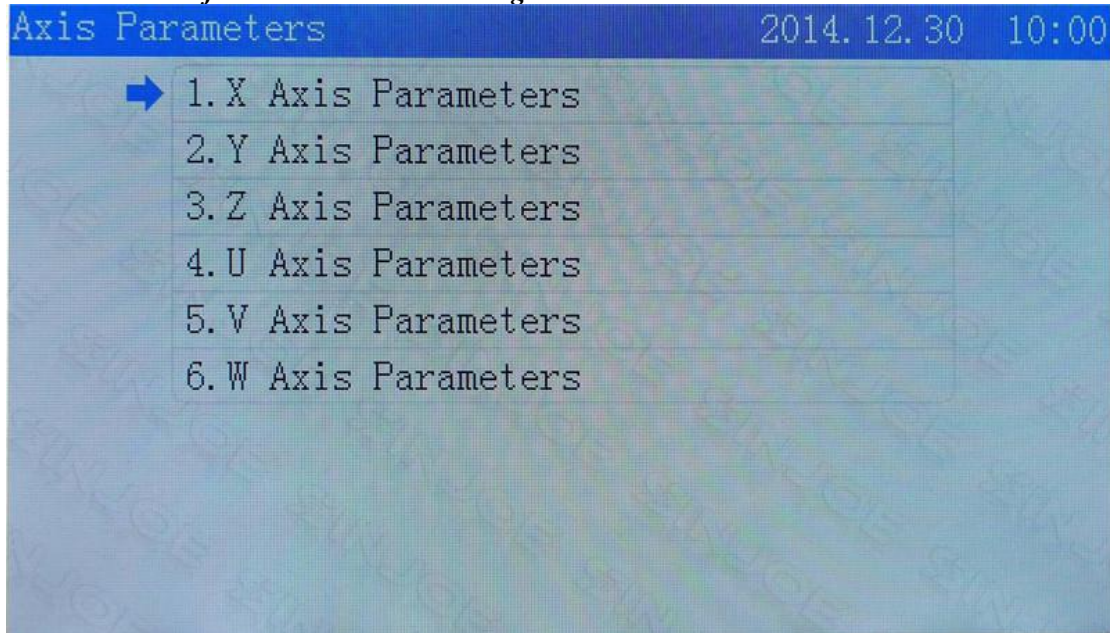
Manufacturer Parameters Settings

Go back to main menu, click key combination of *Stop* and *Shift* to shift to *Manufacturer Parameters Settings*.

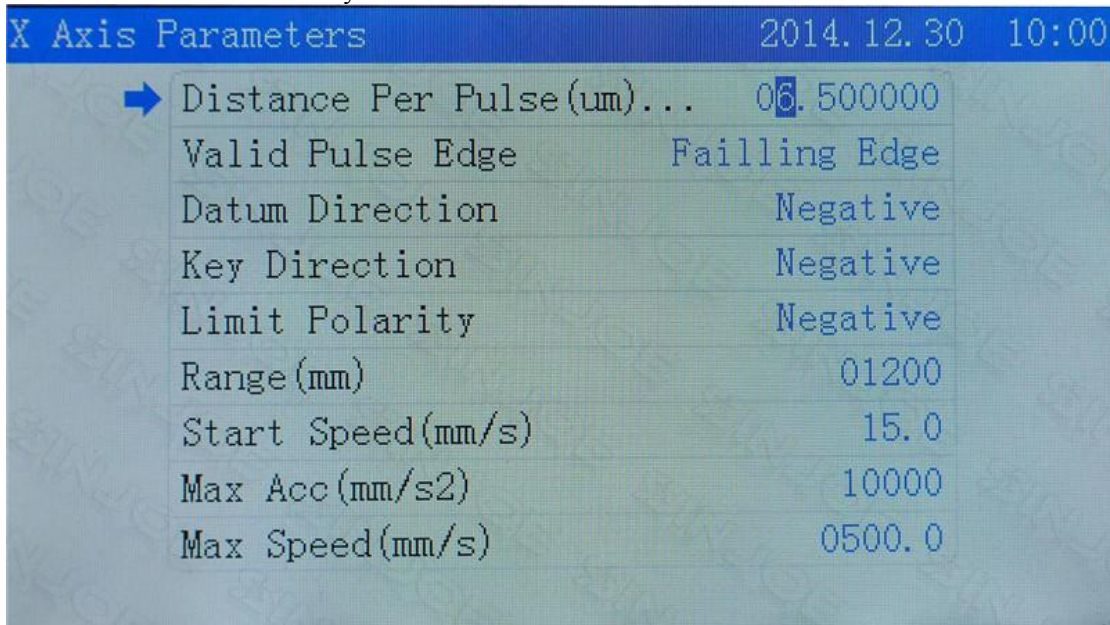


1. Axis Parameters

Go back to **Manufacturer Parameters Settings** and click **Axis Parameters**.



Click **X Axis Parameters** and you will see the interface like below.

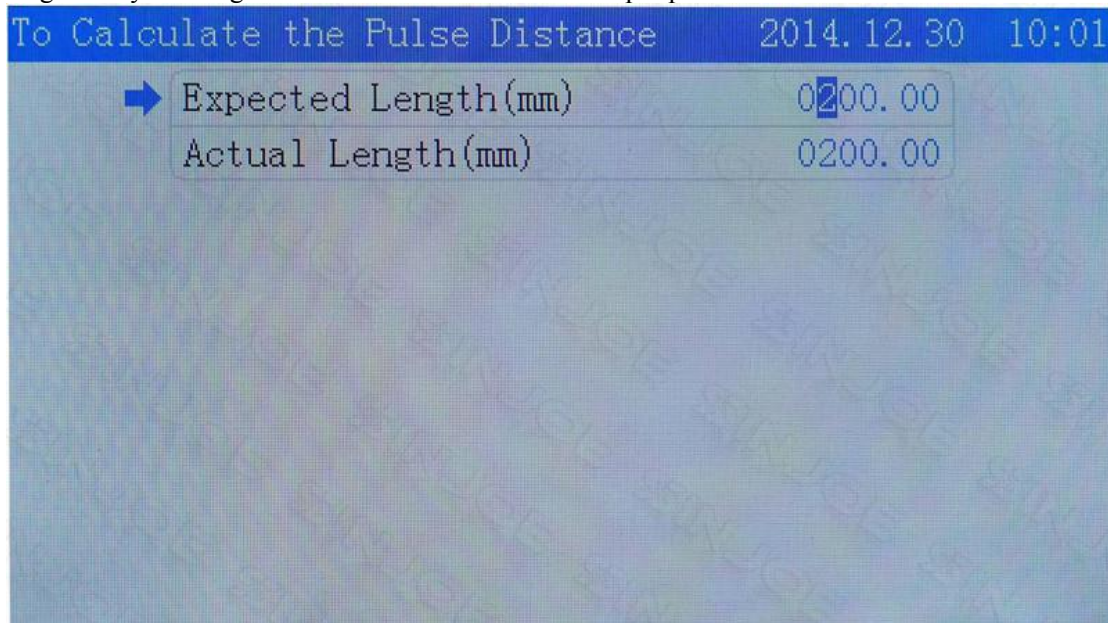


- **Distance Per Pulse(um)**
There is displacement when a single pulse output by motor. Wrong setting will cause pattern deformation.
- **Valid Pulse Edge**
It refers to valid value for logic level change of driver.
- **Datum Direction**
It refers to laser head's moving direction when resetting. Wrong reset will cause deviation for laser head's moving direction.
- **Key Direction**

It refers to laser head's moving direction when pressing arrow key on panel. Wrong setting will cause laser head moving on axis in the opposite direction.

- **Limit Polarity**
Logic level signal sent from limit switch to panel. Wrong setting will cause limit function failure.
- **Range(mm)**
The size of machine's working table.
- **Start Speed(mm/s)**
The initial speed of laser head from static condition to movement.
- **Max Acc(mm/s²)**
It should be filled in number with an increase or decrease of 50 or 100 at a time at least.
- **Max Speed(mm/s)**
Max speed for axis.

Go back to *X Axis Parameters*, click *Distance per Pulse* to modify expected length and actual length and you will get an auto value result of distance per pulse.



2. Laser Parameters

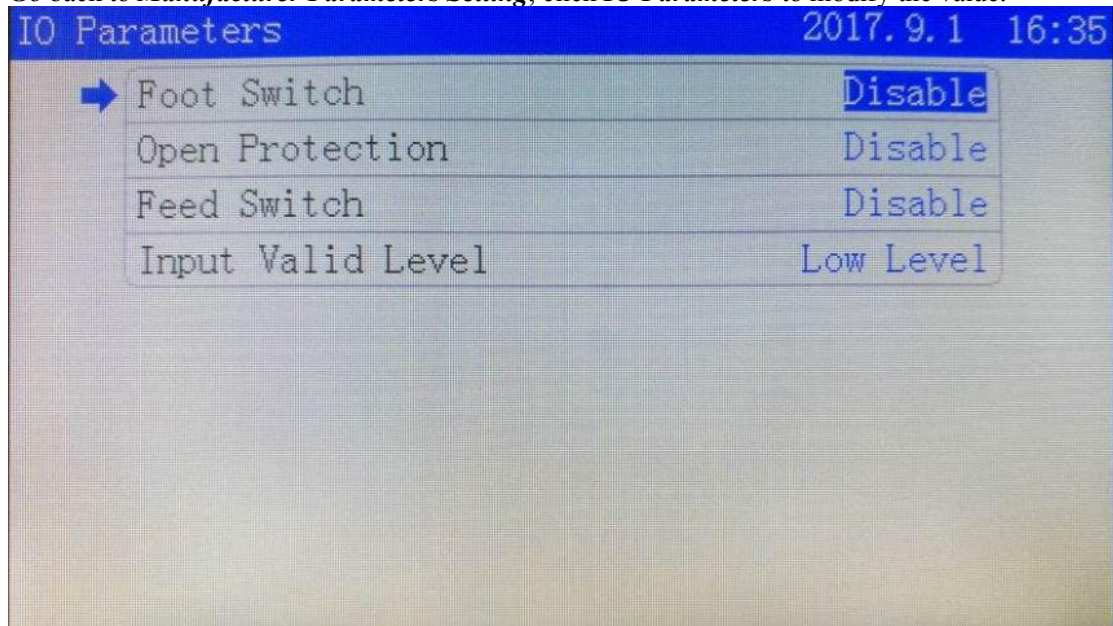
Go back to **Manufacturer Parameters Setting**, click **Laser Parameters** to modify the value.

Laser Parameters		2014.12.30 10:01
→ Laser Mode	CO2 Glass Tube	
TTL Valid Level	Low Level	
PWM Frequency (hz)	20000	
Max Power (%)	98	
RF Min Power (%)	0.0	
Laser1 Water Protect	Close	
Laser2 Water Protect	Close	
Laser3 Water Protect	Close	
Laser4 Water Protect	Close	

- **Laser Mode**
It refers to laser types.
- **TTL Valid Level**
It refers to logic level of laser head.
- **PWM Frequency(hz)**
It is used for setting pulse frequency of control signal for laser.
- **Max Power(%)**
Max power also known as limit power. You may not set the power higher than limit power. The power value will be showed in percent bar.
- **RF Min Power(%)**
Min power of laser tube.
- **Laser Water Protect**
Enable *water protection switch* when required.

3. IO Parameters

Go back to *Manufacturer Parameters Setting*, click *IO Parameters* to modify the value.

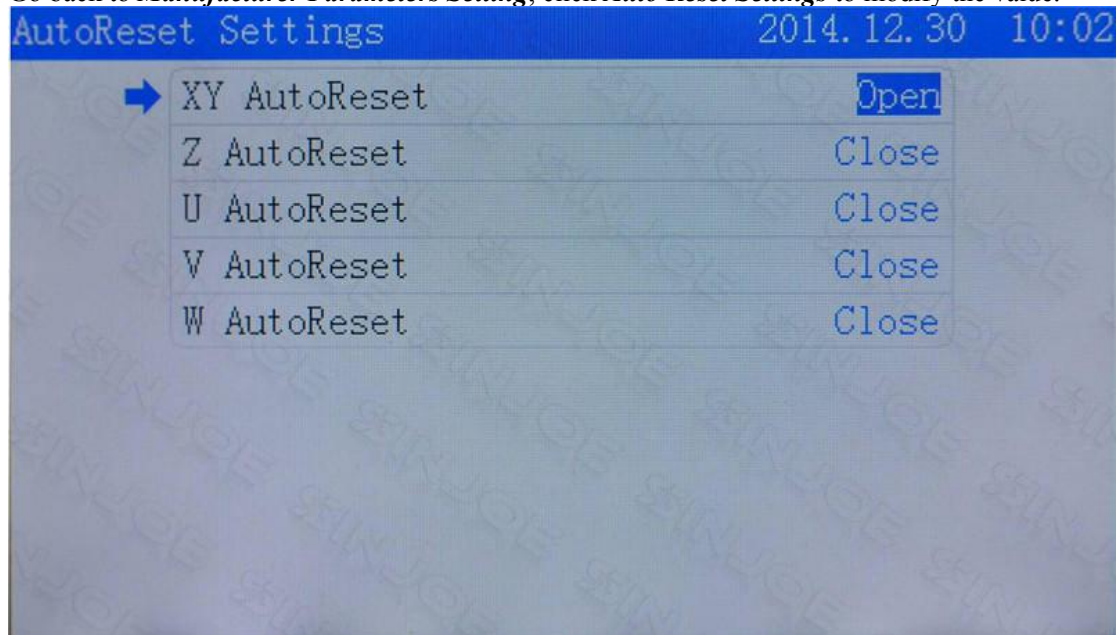


IO Parameters		2017.9.1 16:35
→	Foot Switch	Disable
	Open Protection	Disable
	Feed Switch	Disable
	Input Valid Level	Low Level

- **Foot Switch**
Enable *Foot Switch* when required.
- **Open Protection**
Enable *Open Protection* when required.
- **Feed Switch**
Output signal.
- **Input Valid Level**
High/low level is allowed to selected.

4. Auto Reset Settings

Go back to **Manufacturer Parameters Setting**, click **Auto Reset Settings** to modify the value.

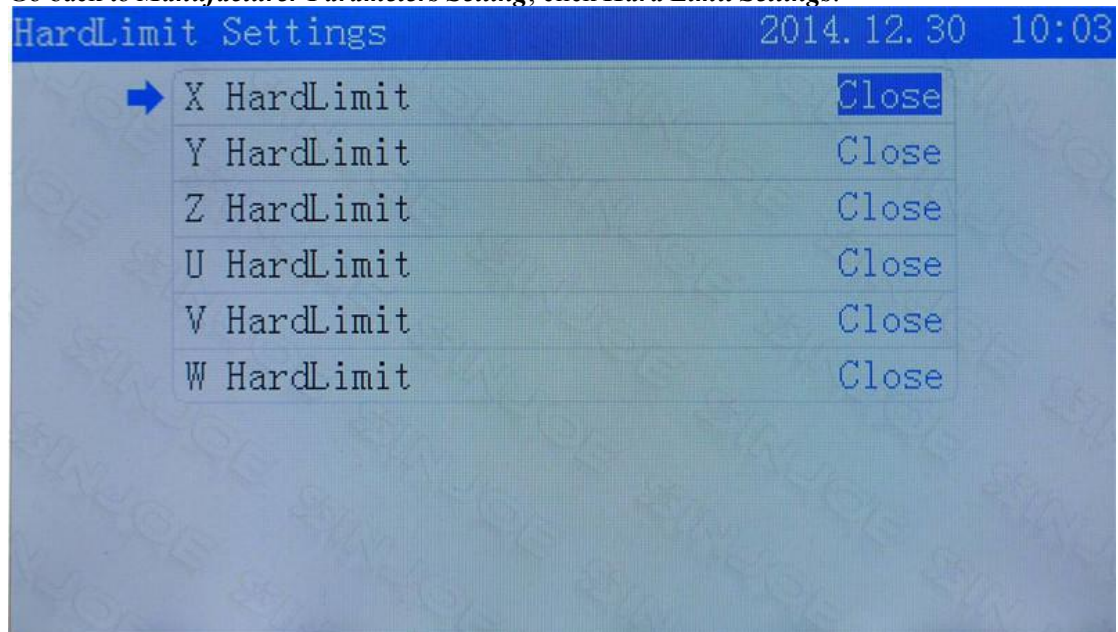


AutoReset Settings		2014.12.30 10:02
→ XY AutoReset		Open
Z AutoReset		Close
U AutoReset		Close
V AutoReset		Close
W AutoReset		Close

- **XY/Z/U/V/W Auto Reset**
Enable *auto reset* when required.

5. Hard Limit Settings

Go back to *Manufacturer Parameters Setting*, click *Hard Limit Settings*.

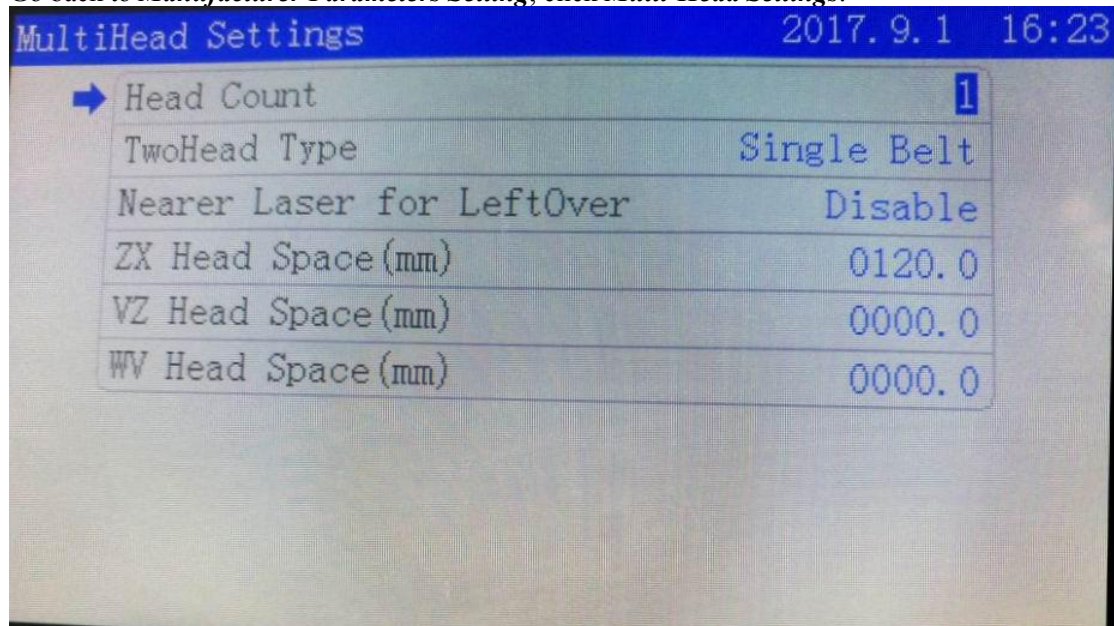


HardLimit Settings		2014.12.30 10:03
→ X HardLimit		Close
Y HardLimit		Close
Z HardLimit		Close
U HardLimit		Close
V HardLimit		Close
W HardLimit		Close

- **X/Y/Z/U/V/W Hard Limit**
Enable *hardware limit switch* when required.

6. Multi-Head Settings

Go back to *Manufacturer Parameters Setting*, click *Multi-Head Settings*.

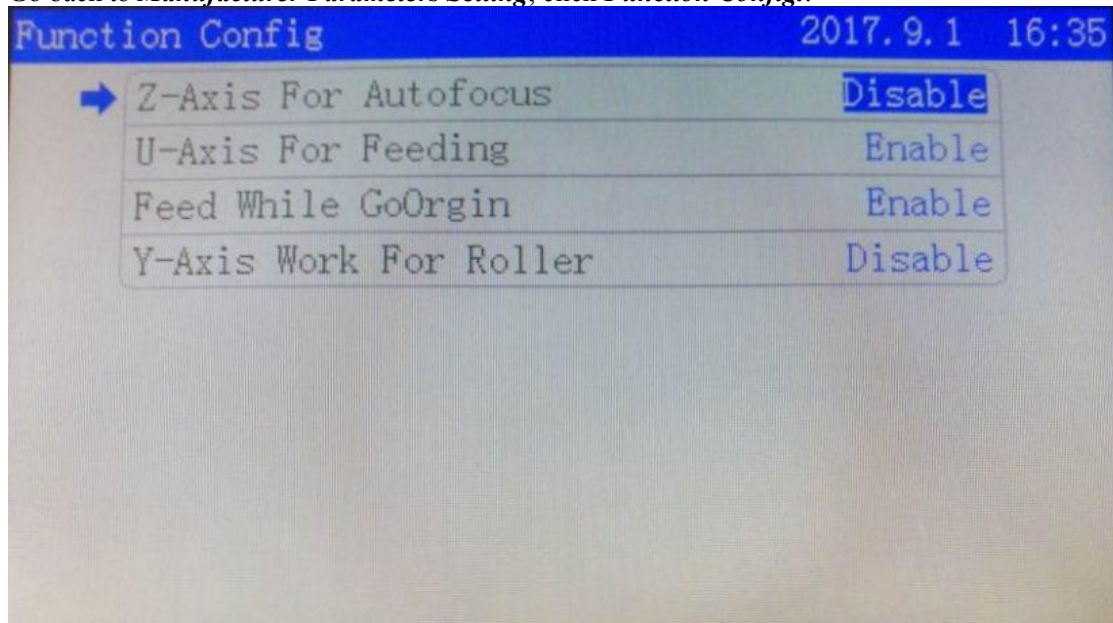


MultiHead Settings		2017.9.1 16:23
→ Head Count		1
TwoHead Type		Single Belt
Nearer Laser for LeftOver		Disable
ZX Head Space (mm)		0120.0
VZ Head Space (mm)		0000.0
WV Head Space (mm)		0000.0

- **Nearer Laser for Leftover**
The proximity principle. The laser head closest to leftover is going to cut it.
- **ZX Head Space**
The distance between X and Z axis (or the first head and second head) after reset. The first and second head here is predicated on reset state and laser head starts ordering from limit switch in axis positive direction.
- **VZ Head Space**
The distance between Z and V axis (or the second head and third head) after reset. The second and third head here is predicated on reset state and laser head starts ordering from limit switch in axis positive direction.
- **WV Head Space**
The distance between V and W axis (or the third head and forth head) after reset. The third and forth head here is predicated on reset state and laser head starts ordering from limit switch in axis positive direction.

7. Function Config

Go back to *Manufacturer Parameters Setting*, click *Function Config*.



Function Config		2017.9.1 16:35
→	Z-Axis For Autofocus	Disable
	U-Axis For Feeding	Enable
	Feed While GoOrigin	Enable
	Y-Axis Work For Roller	Disable

- **Z Axis For Autofocus**
Enable auto focus when required.
- **U For Feeding**
Enable *U For Feeding* when required.
- **Feed While GoOrigin**
Feeding before going back to origin.
- **Y Axis Work For Roller**
For example, cutting a coil of rope.